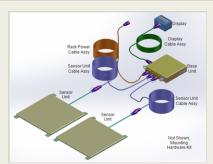
# Enhanced Dynamic Load Sensor for ISS (EDLS-ISS), Phase II



Completed Technology Project (2014 - 2016)

## **Project Introduction**

Aurora Flight Sciences and the Massachusetts Institute of Technology (MIT) propose to develop a stand-alone 6-DOF load sensing system that collects biomechanical force and moment data while integrated with the Advanced Resistive Exercise Device (ARED) on the International Space Station by adapting and enhancing previously field-tested systems. Our EDLS-ISS system includes a separate base unit tethered to two low-profile sensors, which can be non-invasively mounted on the surface of the ARED to serve as new footplates. The EDLS-ISS is being developed for two reasons: - Operational. Force plates on the ARED will allow crewmembers to verify loading, and to record forces. This device provides a simple, non-invasive solution that measures foot forces and displays this to the astronaut. - Research. Kinematic experiments on the ARED – for example, characterizing limb segment relative motions during a squat - require corresponding force and moment measurements. Our EDLS-ISS system provides three-axis force and three-axis moment measurements for such experiments. By providing a short-term operational solution and a sustainable long-term research solution, ELDS-ISS is an important tool for the spaceflight community. During Phase I, we improved the design of the existing 6-DOF Microgravity Investigation of Crew Reactions in 0-G (MICR0-G) Adapt sensor module, previously developed by Aurora and MIT. These improvements optimized the sensor for use on the ARED: decreasing the overall height of the sensors and separating the electronics into an off-board "base unit", increasing the footprint size to cover most of the surface of the ARED platform, updating the hard drive and electronics, providing a real-time user-feedback display, and developing ARED mounting options. The anticipated result of our Phase II effort will be three complete EDLS-ISS systems, each of which includes a base unit and two sensor units. Two systems will be flight-qualified.



Enhanced Dynamic Load Sensor for ISS (EDLS-ISS), Phase II

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# Organizational Responsibility

#### Responsible Mission Directorate:

Space Technology Mission Directorate (STMD)

#### **Responsible Program:**

Small Business Innovation Research/Small Business Tech Transfer



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## **Primary U.S. Work Locations and Key Partners**



Organizations Performing Work	Role	Туре	Location
Johnson Space	Supporting	NASA	Houston,
Center(JSC)	Organization	Center	Texas

Primary U.S. Work Locations	
Massachusetts	Texas

## **Project Transitions**



May 2014: Project Start



September 2016: Closed out

**Closeout Summary:** Enhanced Dynamic Load Sensor for ISS (EDLS-ISS), Phas e II Project Image

#### **Closeout Documentation:**

• Final Summary Chart Image(https://techport.nasa.gov/file/137598)

# **Project Management**

#### **Program Director:**

Jason L Kessler

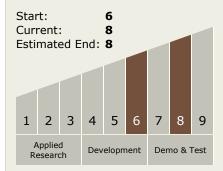
#### **Program Manager:**

Carlos Torrez

#### **Principal Investigator:**

Christopher Krebs

# Technology Maturity (TRL)



# **Technology Areas**

#### **Primary:**

- TX06 Human Health, Life Support, and Habitation Systems
  - ☐ TX06.3 Human Health and Performance
    - □ TX06.3.2 Prevention and Countermeasures



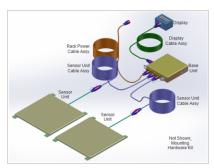
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## **Images**



## **Briefing Chart Image**

Enhanced Dynamic Load Sensor for ISS (EDLS-ISS), Phase II (https://techport.nasa.gov/imag e/136713)



#### **Final Summary Chart Image**

Enhanced Dynamic Load Sensor for ISS (EDLS-ISS), Phase II Project Image (https://techport.nasa.gov/imag

e/127872)

## **Target Destinations**

The Sun, Earth, The Moon, Mars, Others Inside the Solar System, Outside the Solar System

